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// Vahe Karamian - Project 2 - CS 301 - Dr. H. K. Liu
// Filename: Root.cpp

#include <iostream.h>
#include <fstream.h>
#include <iomanip.h>
#include <math.h>

float valueAtPoint( float x, float coefficients[], int N );
void bisectionMethod( float coefficients[], int N );
void quadraticEquation( float coefficients[] );
void newtonMethod( float coefficients[], int N, float c );

int main( )
{
    ifstream dataFile( "Root.dat", ios::in );
    if( !dataFile )
    {
        cout<<"\n Data file not found! \n"<<endl;
        return 0;
    }

    // Step 1 - get the polynomial from the data file
    // Format
    // =====
    // LINE 1: N          1 integer, the number of polynomial
    // LINE 2: An An-1 An-2 ... A1 A0 N+1 floats separated by one space,
    //          coefficients of polynomial

    int N = 0;    // The number of polynomial, initialize to zero

    dataFile >> N; // Get the number of polynomial

    // Create coefficients data array
    float *coefficients = new float[N+1];
    int index = 0; // Index of the coefficient data array

    // Initialize coefficients to zero
    for( int z=0; z<N+1; z++ )
        coefficients[z] = 0;

    // Get the N+1 coefficients
    while( dataFile >> coefficients[index] ) { index++; }

    // Print the polynomial for testing
    cout<<"The root(s) to the polynomial ";
    for( int i=0; i<N+1; i++ )
    {
        cout<<coefficients[i]<<"x^"<<N-i<<" ";
    }
    cout<<"are: \n";

    // Check to see if polynomial is of degree 2
    if( N == 2 )
    {
        quadraticEquation( coefficients );
    }
    else
    {
        // Step 2 - starting from 0.0 use step size 0.5 to find a and b such that
        //          sign( f(a) ) <> sign( f(b) )
        float a = 0.0;
        float b = (float)(a + 0.5);

        while( N > 2 )
        {
            bisectionMethod( coefficients, N );
            N--;
        }
    }

    quadraticEquation( coefficients );

    return 0;
}

void quadraticEquation( float coefficients[] )
{
    // We can use the quadratic equation

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float r1 = (float)( ( -1*coefficients[1] + sqrt( pow(coefficients[1],2) - 4*coefficients[0]*coefficients[2] ) ) / ( 2*
coefficients[0] ) );
float r2 = (float)( ( -1*coefficients[1] - sqrt( pow(coefficients[1],2) - 4*coefficients[0]*coefficients[2] ) ) / ( 2*
coefficients[0] ) );

cout<< r1 <<" "<<r2<<endl;
}

// Calculate the value of the function at point x
float valueAtPoint( float x, float coefficients[], int N )
{
float value = 0.0;          // initialize value to 0.0
for( int i=0; i<N+1; i++ )
    value = (float)(value + (float)( coefficients[i]*pow(x, N-i) ));
return value;              // return value of polynomial at x
}

// Perform Bisection Method 3 Times
void bisectionMethod( float coefficients[], int N )
{
float a1, a2, b1, b2, c, u, v;
float a, b;

b1 = 0.0;
b2 = 0.0;

while( true )
{
// Check to see if sign(u) <> sign(v), in other words
// sign( f(a) ) <> sign( f(b) )

a1 = b1;
b1 = (float)(a1 + 0.5);

u = valueAtPoint( a1, coefficients, N ); // compute f(a)
v = valueAtPoint( b1, coefficients, N ); // compute f(b)

cout<<"a1 = "<<a1<<" f(a1) = "<< u <<endl;
cout<<"b1 = "<<b1<<" f(b1) = "<< v <<endl;

if( (u < 0 && v > 0) || (u > 0 && v < 0) )
{
a = a1;
b = b1;
break;
}

a2 = b2;
b2 = (float)(a2 - 0.5);

u = valueAtPoint( a2, coefficients, N ); // compute f(a)
v = valueAtPoint( b2, coefficients, N ); // compute f(b)

cout<<"a2 = "<<a2<<" f(a2) = "<< u <<endl;
cout<<"b2 = "<<b2<<" f(b2) = "<< v <<endl;

if( (u < 0 && v > 0) || (u > 0 && v < 0) )
{
a = a2;
b = b2;
break;
}
}

// Do 3 iterations of Bisection Method
for( int i=0; i<3; i++ )
{
c = (float) ( (a+b)/2 );
if( c == 0 )
{
// we found a root print and break
cout<<c;
return;
}
else
{
u = valueAtPoint( a, coefficients, N );
v = valueAtPoint( b, coefficients, N );
}
}
}

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// Check to see if sign(u) <> sign(v), in other words
// sign( f(a) ) <> sign( f(b) )
if( (u < 0 && v > 0) || (u > 0 && v < 0) )
{
    b = c;
}
else
{
    a = c;
}
}
}

c = (float)( (a+b)/2 );

// cout<<"a = "<<a<<"and b = "<<b<<" which makes c = "<< c <<endl;
// cout<<"One of the roots is "<< c <<" using Bisection Method with 3 iterations"<<endl;

// Use Newton's Method to find the root
newtonMethod( coefficients, N, c );
}

void newtonMethod( float coefficients[], int N, float c )
{
    // code here ...
}

```